Economical Dual Display type, PID Control

Features
- Realizes ideal temp. controlling with newly developed PID control algorithm and 100ms high speed sampling
- Built-in relay output or SSR drive output selectable: Enables to phase control and cycle control with SSR drive output(SSRP function)
- Dramatically increased visibility using wide display part
- Enhanced convenience of wiring and maintenance by connector plug type (TCN4S-P)
- Mounting space saving with compact design: Approx. 38% reduced size compared with existing model(depth-based)

Ordering information

<table>
<thead>
<tr>
<th>T</th>
<th>CN</th>
<th>4</th>
<th>S</th>
<th>2</th>
<th>4</th>
<th>R</th>
<th>P</th>
</tr>
</thead>
<tbody>
<tr>
<td>Wiring method</td>
<td>Control output</td>
<td>Power supply</td>
<td>Auxiliary output</td>
<td></td>
<td></td>
<td></td>
<td></td>
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<tr>
<td>No-mark</td>
<td>Bolt wiring method</td>
<td></td>
<td></td>
<td></td>
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</tr>
<tr>
<td>P</td>
<td>Connector plug connection method1</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>R</td>
<td>Relay contact output+SSR drive output2</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>2</td>
<td>Alarm1+Alarm2 output</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>2</td>
<td>24VAC 50/60Hz, 24-48VDC</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>4</td>
<td>100-240VAC 50/60Hz</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>4</td>
<td>DIN W48×H48mm</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>S</td>
<td>DIN W72×H72mm</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>M</td>
<td>DIN W48×H96mm</td>
<td></td>
<td></td>
<td></td>
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<td></td>
<td></td>
</tr>
<tr>
<td>H</td>
<td>DIN W96×H96mm</td>
<td></td>
<td></td>
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<td></td>
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<td></td>
</tr>
<tr>
<td>4</td>
<td>9999(4digit)</td>
<td></td>
<td></td>
<td></td>
<td></td>
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<td></td>
</tr>
<tr>
<td>CN</td>
<td>Dual display type, set by touch switch</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>T</td>
<td>Temperature controller</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

1: Only for TCN4S model.
2: In case of the AC voltage model, SSR drive output method (standard ON/OFF control, cycle control, phase control) is available to select.

Specifications

<table>
<thead>
<tr>
<th>Series</th>
<th>TCN4S</th>
<th>TCN4M</th>
<th>TCN4H</th>
<th>TCN4L</th>
</tr>
</thead>
<tbody>
<tr>
<td>Power supply</td>
<td>AC power</td>
<td>100-240VAC 50/60Hz</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>AC/DC power</td>
<td>24VAC 50/60Hz, 24-48VDC</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Allowable voltage range</td>
<td>90 to 110% of rated voltage</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Power consumption</td>
<td>AC power</td>
<td>Max. 5VA(100-240VAC 50/60Hz)</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>AC/DC power</td>
<td>Max. 5VA(24VAC 50/60Hz), Max. 3W(24-48VDC)</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Display method</td>
<td>7 Segment (PV: red, SV: green), Other display (green, red) LED</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Character size</td>
<td>PV(W×H)</td>
<td>7.0×15.0mm</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>SV(W×H)</td>
<td>5.0×9.5mm</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Input type</td>
<td>RTD</td>
<td>DPt100Ω, Cu50Ω (allowable line resistance max. 5Ω per a wire)</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>Thermocouple</td>
<td>K(CA), J(IC), L(IC), T(CC), R(PR), S(PR)</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Display accuracy</td>
<td>RTD</td>
<td>±0.5%+1digit</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>Thermocouple</td>
<td>±0.5%+1digit</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Control output</td>
<td>Relay</td>
<td>250VAC 3A 1a</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Alarm output</td>
<td>SSR</td>
<td>12VDC ±2V 20mA Max.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Control method</td>
<td>ON/OFF control, P, PI, PID control</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Hysteresis</td>
<td>1 to 100°C/°F (0.1 to 50.0°C/F) variable</td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

1: ① At room temperature (23°C ±5°C)
- Thermocouple R(PR), S(PR), below 200°C: (PV ±0.5% or ±3°C, select the higher one) ±1digit
- Thermocouple R(PR), S(PR), over 200°C: (PV ±0.5% or ±2°C, select the higher one) ±1digit
- Thermocouple L(IC), RTD Cu500Ω: (PV ±0.5% or ±2°C, select the higher one) ±1digit
② Out of room temperature range
- Thermocouple R(PR), S(PR), below 200°C: (PV ±1.0% or ±6°C, select the higher one) ±1digit
- Thermocouple R(PR), S(PR), over 200°C: (PV ±0.5% or ±5°C, select the higher one) ±1digit
- Thermocouple L(IC), RTD Cu500Ω: (PV ±0.5% or ±3°C, select the higher one) ±1digit
For TCN4S-P, add ±1°C by accuracy standard.
# TCN Series

## Specifications

<table>
<thead>
<tr>
<th>Series</th>
<th>TCN4S</th>
<th>TCN4M</th>
<th>TCN4H</th>
<th>TCN4L</th>
</tr>
</thead>
<tbody>
<tr>
<td>Proportional band (P)</td>
<td>0.1 to 999.9°C/F</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Integral time (I)</td>
<td>0 to 9999 sec.</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Derivative time (D)</td>
<td>0 to 9999 sec.</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Control period (T)</td>
<td>0.5 to 120.0 sec.</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Manual reset</td>
<td>0.0 to 100.0%</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Sampling period</td>
<td>100ms</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Dielectric strength AC Power</td>
<td>2,000VAC 50/60Hz 1min. (between input terminal and power terminal)</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>AC/DC Power</td>
<td>1,000VAC 50/60Hz 1min. (between input terminal and power terminal)</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Vibration</td>
<td>0.75mm amplitude at frequency of 5 to 55Hz in each of X, Y, Z directions for 2 hours</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Relay life cycle Mechanical</td>
<td>OUT: Over 5,000,000 times, AL1/2: Over 5,000,000 times</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Electrical</td>
<td>OUT: Over 200,000 times (250VAC 3A resistive load) AL1/2: Over 300,000 times (250VAC 1A resistive load)</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Insulation resistance</td>
<td>Min. 100MQ (at 500VDC megger)</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Noise resistance</td>
<td>±2kV R-phase, S-phase the square wave noise (pulse width: 1us) by the noise simulator</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Memory retention</td>
<td>Approx. 10 years (when using non-volatile semiconductor memory type)</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Environment Ambient temperature</td>
<td>-10 to 50°C, storage: -20 to 60°C</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Ambient humidity</td>
<td>35 to 85%RH, storage: 35 to 85%RH</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Insulation type</td>
<td>Double insulation or reinforced insulation (mark: Dielectric strength between the measuring input part and the power part: AC power 2kV, AC/DC Power 1kV)</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Approval</td>
<td>(except TCN4S-*)</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Weight±2</td>
<td>Approx. 147g (Approx. 100g)</td>
<td>Approx. 203g (Approx. 133g)</td>
<td>Approx. 194g (Approx. 124g)</td>
<td>Approx. 275g (Approx. 179g)</td>
</tr>
</tbody>
</table>

※2: The weight is with packaging and the weight in parentheses is only unit weight.
※Environment resistance is rated at no freezing or condensation.

## Connections

※TCN4 Series has selectable control output; Relay output, and SSR drive output. AC/DC voltage type does not have SSRP function.

### TCN4S

- SSR OUT: 12VDC ±2V 20mA Max.
- AL1 OUT: 250VAC 1A 1a
- AL2 OUT: 250VAC 1A 1a

### TCN4S-+P

- SSR OUT: 12VDC ±2V 20mA Max.
- AL1 OUT: 250VAC 1A 1a
- AL2 OUT: 250VAC 1A 1a

### TCN4M

- SSR OUT: 12VDC ±2V 20mA Max.
- AL1 OUT: 250VAC 1A 1a
- AL2 OUT: 250VAC 1A 1a

### TCN4H/L

- SSR OUT: 12VDC ±2V 20mA Max.
- AL1 OUT: 250VAC 1A 1a
- AL2 OUT: 250VAC 1A 1a

※1: Power supply
- AC power: 100-240VAC 5VA 50/60Hz
- AC/DC power: 24VAC 5VA 50/60Hz, 24-48VDC 3W
Economical Dual Display type, PID Control

**Dimensions**

[A] Photoelectric sensor
[B] Fiber optic sensor
[C] Door/Area sensor
[D] Proximity sensor
[E] Pressure sensor
[F] Rotary encoder
[G] Connector/Socket
[H] Temp. controller
[I] SSR/Power controller
[J] Counter
[K] Panel meter
[L] Tacho/Speed/Pulse meter
[M] Display unit
[N] Sensor controller
[O] Switching mode power supply
[P] Stepper motor/Driver/Controller
[Q] Graphic/Logic panel
[R] Field network device
[S] Software
[T] Other

<table>
<thead>
<tr>
<th>Dimensions</th>
<th>TCN4S</th>
<th>TCN4S-P</th>
<th>TCN4M</th>
<th>TCN4H</th>
<th>TCN4L</th>
</tr>
</thead>
<tbody>
<tr>
<td>TCN4S</td>
<td><img src="image1" alt="TCN4S Diagram" /></td>
<td><img src="image2" alt="TCN4S-P Diagram" /></td>
<td><img src="image3" alt="TCN4M Diagram" /></td>
<td><img src="image4" alt="TCN4H Diagram" /></td>
<td><img src="image5" alt="TCN4L Diagram" /></td>
</tr>
<tr>
<td>TCN4M</td>
<td><img src="image6" alt="TCN4M Diagram" /></td>
<td><img src="image7" alt="TCN4M Diagram" /></td>
<td><img src="image8" alt="TCN4M Diagram" /></td>
<td><img src="image9" alt="TCN4M Diagram" /></td>
<td><img src="image10" alt="TCN4M Diagram" /></td>
</tr>
<tr>
<td>TCN4H</td>
<td><img src="image11" alt="TCN4H Diagram" /></td>
<td><img src="image12" alt="TCN4H Diagram" /></td>
<td><img src="image13" alt="TCN4H Diagram" /></td>
<td><img src="image14" alt="TCN4H Diagram" /></td>
<td><img src="image15" alt="TCN4H Diagram" /></td>
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<tr>
<td>TCN4L</td>
<td><img src="image16" alt="TCN4L Diagram" /></td>
<td><img src="image17" alt="TCN4L Diagram" /></td>
<td><img src="image18" alt="TCN4L Diagram" /></td>
<td><img src="image19" alt="TCN4L Diagram" /></td>
<td><img src="image20" alt="TCN4L Diagram" /></td>
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</tbody>
</table>

**Panel cut-out**

<table>
<thead>
<tr>
<th>Size</th>
<th>A</th>
<th>B</th>
<th>C</th>
<th>D</th>
</tr>
</thead>
<tbody>
<tr>
<td>TCN4S</td>
<td>Min. 65</td>
<td>Min. 65</td>
<td>45''</td>
<td>45''</td>
</tr>
<tr>
<td>TCN4M</td>
<td>Min. 90</td>
<td>Min. 90</td>
<td>68''</td>
<td>68''</td>
</tr>
<tr>
<td>TCN4H</td>
<td>Min. 65</td>
<td>Min. 115</td>
<td>45''</td>
<td>92''</td>
</tr>
<tr>
<td>TCN4L</td>
<td>Min. 115</td>
<td>Min. 115</td>
<td>92''</td>
<td>92''</td>
</tr>
</tbody>
</table>

**Bracket**

- **TCN4S Series**
  - ![Bracket TCN4S Diagram](image21)
- **TCN4M, TCN4H, TCN4L Series**
  - ![Bracket TCN4M, TCN4H, TCN4L Diagram](image22)
TCN Series

## Dimensions

### Terminal cover(sold separately)

- **RSA-COVER** (48×48mm)
- **RMA-COVER** (72×72mm)
- **RHA-COVER** (48×96mm)
- **RLA-COVER** (96×96mm)

![Terminal cover dimensions](image)

### Parts description

1. **Present temperature (PV) display (red)**
   - RUN mode: Present temperature (PV) display.
   - Parameter setting mode: Parameter display.

2. **Set temperature (SV) display (green)**
   - RUN mode: Set temperature (SV) display.
   - Parameter setting mode: Parameter setting value display.

3. **Control/Alarm output display indicator**
   - OUT: It turns ON when the control output is ON.
   - During SSR drive output type in CYCLE/PHASE control, this indicator turns ON when MV is over 3.0%.
   - AL1/AL2: It turns ON when the alarm output is ON.

4. **Auto tuning indicator**: AT indicator flashes by every 1 sec during operating auto tuning.

5. **MODE key**: Used when entering into parameter setting group, returning to RUN mode, moving parameter, and saving setting values.

6. **Adjustment**: Used when entering into set value change mode, digit moving and digit up/down.

7. **Digital input key**: Press [up] + [down] keys for 3 sec. to operate the set function(RUN/STOP, alarm output reset, auto tuning) in digital input key [d1 - d4].

8. **Temperature unit(°C/°F) indicator**: It shows current temperature unit.

## SV setting

You can set the temperature to control with **MODE**, [up], [down] keys. Set range is within SV lower limit value [L - 5U] to SV higher limit value [H - 5U].

**Ex)** In case of changing set temperature from 210°C to 250°C

1. Press any key among **MODE**, [up], [down] key in RUN mode, the right digit at SV display flashes and it enters to SV setting.

2. Press [up] key to move the desired digit. (10^0 → 10^-1 → 10^-2 → 10^-3 → 10^-4)

3. Press [up] or [down] key to move the desired number (1 → 5).

4. Press **MODE** key to save the value and it controls with this set value. (even though there is no key input for over 3 sec., it saves automatically.)
Parameter setting group

Run mode

Press any key among

MO(4) 2 sec.

MO(4) 4 sec.

SV setting

Parameter 1 group

Parameter 2 group

AL1 alarm temperature

AL2 alarm temperature

Auto tuning

Proportional band

Integral time

Derivative time

Manual reset

Hysteresis

MODE 3 sec.

Input sensor

Input sensor

Control type

Control output operation

Control output type

Control output operation

LBA detection band

LBA monitoring time

Digital input key

Digital input key

Control output MV in case of input break error

Control output MV in case of input break error

AL1 alarm operation mode

AL2 alarm operation mode

0n-b

0n-b

C-4d

α-4b

LbRb

LbRb

4l-4b

4l-4b

HYS

HYS

HYS

HYS

L-Su

L-Su

IL

IL

RL-1

RL-2

※Press <MODE> key over 3 sec in any setting group, it saves the set value and returns to RUN mode.
(Press <MODE> key once in SV setting, it returns to RUN mode).
※If no key entered for 30 sec., it returns to RUN mode automatically and the set value of parameter is not be saved.
※Press <MODE> key again within 1 sec. after returning to RUN mode, it advances of the first parameter of previous setting group.
※Press <MODE> key to move next parameter.
※This parameter might not be displayed depending on other parameter settings.
※Set parameter as ‘Parameter 2 group → Parameter 1 group → Setting of set value’ order considering parameter relation of each setting group.
※1: It is not displayed for AC/DC power model (TCN4□-22R).
TCN Series

Parameter 1 group

- **Run mode**: Press any key among \( \mathbb{C} \), \( \mathbb{S} \), \( \mathbb{L} \) to enter Run mode.

- **3 sec.**: After checking or changing setting value in each parameter, press the MODE key to save and move to next parameter setting.

- **2 sec.**: It is displayed when control type parameter [C - h_d] of parameter 2 group is set Pr.d.

- **Alarm temperature**: Press the MODE key for 3 sec. to return RUN mode at any parameter.

- **This parameter might not be displayed depending on other parameter settings.**

- **Set range**: Deviation alarm (F.S to F.S). Absolute value alarm (temperature range)

- **In case alarm operation mode [AL - 1] of Parameter 2 group is R\( \text{A}_{L} \), Sb\( \text{R}_{L} \), \( \text{R}_{L} \), no parameters is displayed.**

- **Set range**: Deviation alarm (F.S to F.S). Absolute value alarm (temperature range)

- **In case alarm operation mode [AL - 2] of Parameter 2 group is R\( \text{A}_{L} \), Sb\( \text{R}_{L} \), \( \text{R}_{L} \), no parameters is displayed.**

Parameter 2 group

- **Run mode**: Press any key among \( \mathbb{C} \), \( \mathbb{S} \), \( \mathbb{L} \) to enter Run mode.

- **4 sec.**: After checking or changing setting value in each parameter, press the MODE key to save and move to next parameter setting.

- **3 sec.**: It is displayed when control type parameter [C - h_d] of parameter 2 group is set Pr.d.

- **Press the MODE key for 3 sec. to return RUN mode at any parameter.**

- **This parameter might not be displayed depending on other parameter settings.**

- **Set range**: Refer to 'Input sensor and temperature range'.

- **If changing input sensor, SV, n-b, H-Su, L-Su, AL1, AL2, LbRb, LbRb, RHYS parameter values are initialized.**

- **Set range**: Deviation alarm (F.S to F.S). Absolute value alarm (temperature range)

- **If changing temperature unit, SV, n-b, H-Su, L-Su, AL1, AL2, LbRb, LbRb, RHYS parameter values are initialized.**

- **Input correction**: Set range

- **Input digital filter**: Set range 0.1 to 120.0sec.
Economical Dual Display type, PID Control

**SV low-limit value**

- **L-SV**: Set range: Within the rated temperature range by input sensor \([L - SV \leq (H - SV - 1)\])
  - In case of changing input sensor type \([\leq \cdot - \cdot]\), it changes automatically as min. value of the changed input sensor.

**SV high-limit value**

- **H-SV**: Set range: Within the rated temperature range by input sensor \([H - SV \geq (L - SV + 1)\])
  - In case of changing input sensor type \([\leq \cdot - \cdot]\), it changes automatically as max. value of the changed input sensor.

**Control output operation**

- **a-fb**: Set range: When changing control output operation, \(\varepsilon \cdot \nu\) is initialized.

**Control type**

- **L-nd**: Set range: When changing control type, \(\varepsilon \cdot \nu\) is initialized (control output MV is below 100%) and \(d - t\) turns OFF automatically.

**Control output type**

- **a-uc**: Set range: It is displayed when selecting control output \([a-uc]\) as \(SSr\). It is not displayed for AC/DC power model (TCN4 [□-22R]).

**SSR drive output method**

- **Scnd**: Set range: 0.5 to 120.0 sec.
  - In case of Relay output \([\cdot \cdot\cdot]\) of control output \([a-uc]\) it is set as 20.0 sec.
  - In case of SSR drive output \([SSr]\) of that, it is set as 2.0 sec.
  - \(\varepsilon\) is not displayed when SSR drive output \([SSr]\) method is set as \(CYCL, PHAS\).

**AL1 alarm operation mode**

- **AL-1**: Refer to Functions 'a Alarm'.
  - \(\varepsilon\)Black: Flashes, Gray: Fixed
  - When changing AL1, AL2 alarm operation mode, AL1, AL2 alarm temperature value are initialized.

**AL2 alarm operation mode**

- **AL-2**: Refer to Functions 'a Alarm output hysteresis'.
  - \(\varepsilon\)RHS is not displayed when AL1, AL2 alarm operation mode \([AL-1, AL-2]\) is set as \(RAQ, 5Bh\) and \(LB\).

**Alarm output hysteresis**

- **RHY**: Set range: 0 to 9999 sec.
  - \(\varepsilon\)'0' is set, loop break alarm function is OFF.
  - \(\varepsilon\)'LB' is displayed when AL1, AL2 alarm operation mode \([AL-1, AL-2]\) is set as \(LB\).

**LBA monitoring time**

- **LBA**: Set range: 0 to 9999 sec.
  - \(\varepsilon\)'0' is set, loop break alarm function is OFF.
  - \(\varepsilon\)'LB' is displayed when AL1, AL2 alarm operation mode \([AL-1, AL-2]\) is set as \(LB\).

**LBA detection band**

- **LBA**: Set range: 0 to 999 (0.0 to 999.9°C/F)
  - \(\varepsilon\)'LB' is displayed when AL1, AL2 alarm operation mode \([AL-1, AL-2]\) is set as \(LB\).

**Digital input key**

- **D1 - D4**: Press \(\#\) and \(\#\) keys for 3 sec. and it executes the set function. For more information, refer to Functions 'a Digital input key'.

**Control output MV in case of input break error**

- **Er-nu**: Set range: 0.0 to 100.0%
  - Only 0.0, 100.0% are displayed when control type \([\cdot - \cdot\cdot]\) is set as \(a-nf\). 
  - When changing PID control to ON/OFF control, if MV is below 100.0%, it is initialized as 0.0%.

**Lock setting**

- **LOC**: Locks parameter 2 group
  - **LOC2**: Locks parameter 1, 2 group
  - **LOC3**: Locks parameter 1, 2 group and SV setting
  - Parameter setting values are still possible to check while Lock mode is ON.
## Input type and range

<table>
<thead>
<tr>
<th>Input sensor</th>
<th>Display</th>
<th>Temperature range (°C)</th>
<th>Temperature range (°F)</th>
</tr>
</thead>
<tbody>
<tr>
<td>K(CA)</td>
<td>TC rH</td>
<td>-50 to 1200</td>
<td>-58 to 2192</td>
</tr>
<tr>
<td></td>
<td>TC rL</td>
<td>-50.0 to 999.9</td>
<td>-58.0 to 999.9</td>
</tr>
<tr>
<td>J(IC)</td>
<td>JI CH</td>
<td>-30 to 800</td>
<td>-22 to 1472</td>
</tr>
<tr>
<td></td>
<td>JI CL</td>
<td>-30.0 to 800.0</td>
<td>-22.0 to 999.9</td>
</tr>
<tr>
<td>L(IC)</td>
<td>LL CH</td>
<td>-40 to 800</td>
<td>-40 to 1472</td>
</tr>
<tr>
<td></td>
<td>LL CL</td>
<td>-40.0 to 800.0</td>
<td>-40 to 999.9</td>
</tr>
<tr>
<td>T(CC)</td>
<td>TC cH</td>
<td>-50 to 400</td>
<td>-58 to 752</td>
</tr>
<tr>
<td></td>
<td>TC cL</td>
<td>-50.0 to 400.0</td>
<td>-58.0 to 752.0</td>
</tr>
<tr>
<td>R(PR)</td>
<td>r Pr</td>
<td>0 to 1700</td>
<td>32 to 3092</td>
</tr>
<tr>
<td>S(PR)</td>
<td>S Pr</td>
<td>0 to 1700</td>
<td>32 to 3092</td>
</tr>
<tr>
<td>RTD</td>
<td>DP t100Ω</td>
<td>dP tH</td>
<td>-100.0 to 400.0</td>
</tr>
<tr>
<td></td>
<td></td>
<td>dP tL</td>
<td>-100.0 to 400.0</td>
</tr>
<tr>
<td></td>
<td>Cu 50Ω</td>
<td>C U SH</td>
<td>-50.0 to 200.0</td>
</tr>
<tr>
<td></td>
<td></td>
<td>C U SL</td>
<td>-50.0 to 200.0</td>
</tr>
</tbody>
</table>

### Factory default

#### ● SV setting

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Factory default</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>0</td>
</tr>
</tbody>
</table>

#### ● Parameter 1 group

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Factory default</th>
<th>Parameter</th>
<th>Factory default</th>
<th>Parameter</th>
<th>Factory default</th>
<th>Parameter</th>
<th>Factory default</th>
</tr>
</thead>
<tbody>
<tr>
<td>AL 1</td>
<td>1250</td>
<td>R</td>
<td>oFF</td>
<td>I</td>
<td>0000</td>
<td>r E5c</td>
<td>0500</td>
</tr>
<tr>
<td>AL 2</td>
<td>1250</td>
<td>P</td>
<td>0 100</td>
<td>d</td>
<td>0000</td>
<td>HYS</td>
<td>002</td>
</tr>
</tbody>
</table>

#### ● Parameter 2 group

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Factory default</th>
<th>Parameter</th>
<th>Factory default</th>
<th>Parameter</th>
<th>Factory default</th>
<th>Parameter</th>
<th>Factory default</th>
</tr>
</thead>
<tbody>
<tr>
<td>L n t</td>
<td>tC rH</td>
<td>H 5 u</td>
<td>1200</td>
<td>t</td>
<td>0200</td>
<td>L b Rb</td>
<td>0002</td>
</tr>
<tr>
<td>U n t</td>
<td>PC</td>
<td>o F t</td>
<td>HEAT</td>
<td>R L 1</td>
<td>R A 1 A</td>
<td>d 1 - t</td>
<td>5 t o P</td>
</tr>
<tr>
<td>L n b</td>
<td>0000</td>
<td>c - A d</td>
<td>P 1 d</td>
<td>L A 2</td>
<td>R A 2 A</td>
<td>E r A u</td>
<td>0000</td>
</tr>
<tr>
<td>mR u F</td>
<td>000.1</td>
<td>o Ut</td>
<td>r LY</td>
<td>R H Y S</td>
<td>00 1</td>
<td>L o C</td>
<td>oFF</td>
</tr>
<tr>
<td>L - 5 u</td>
<td>- 050</td>
<td>55 r A</td>
<td>5 t nd</td>
<td>L b R b</td>
<td>0000</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

*The AC/DC voltage models do not have SSR drive output method[55r A]. In case of control output [ o Ut], if set as 55r, it supports only ON/OFF output.*

### Product mounting

#### ● TCN4S(48×48mm) Series

※Mount the product on the panel, fasten bracket by pushing with tools as shown above.

#### ● Other Series
Functions

Alarm [RL-1/RL-2]

There are two alarms which operate individually. You can set combined alarm operation and alarm option. Use digital input key (set as RL, E) or turn OFF power and re-start this unit to release alarm operation.

Alarm operation

<table>
<thead>
<tr>
<th>Mode</th>
<th>Name</th>
<th>Alarm operation</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>R5R6</td>
<td>———</td>
<td>———</td>
<td>No alarm output</td>
</tr>
<tr>
<td>R5R1</td>
<td>Deviation high-limit alarm</td>
<td>OFF ON</td>
<td>If deviation between PV and SV as high-limit is higher than set value of deviation temperature, the alarm output will be ON.</td>
</tr>
<tr>
<td>R5R2</td>
<td>Deviation low-limit alarm</td>
<td>ON OFF</td>
<td>If deviation between PV and SV as low-limit is higher than set value of deviation temperature, the alarm output will be ON.</td>
</tr>
<tr>
<td>R5R3</td>
<td>Deviation high/low-limit alarm</td>
<td>ON OFF</td>
<td>If deviation between PV and SV as high/low-limit is higher than set value of deviation temperature, the alarm output will be ON.</td>
</tr>
<tr>
<td>R5R4</td>
<td>Deviation high/low-limit reverse alarm</td>
<td>ON OFF</td>
<td>If deviation between PV and SV as high/low-limit is higher than set value of deviation temperature, the alarm output will be OFF.</td>
</tr>
<tr>
<td>R5R5</td>
<td>Absolute value high limit alarm</td>
<td>OFF ON</td>
<td>If PV is higher than the absolute value, the output will be ON.</td>
</tr>
<tr>
<td>R5R6</td>
<td>Absolute value low limit alarm</td>
<td>ON OFF</td>
<td>If PV is lower than the absolute value, the output will be ON.</td>
</tr>
</tbody>
</table>

Sensor break Alarm ———

It will be ON when it detects sensor disconnection.

Loop break Alarm ———

It will be ON when it detects loop break.

Alarm option

<table>
<thead>
<tr>
<th>Mode</th>
<th>Name</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>R1R6</td>
<td>Standard alarm</td>
<td>If it is an alarm condition, alarm output is ON. If it is a clear alarm condition, alarm output is OFF.</td>
</tr>
<tr>
<td>R1R7</td>
<td>Alarm latch</td>
<td>It is an alarm condition, alarm output is ON and maintains ON status.</td>
</tr>
<tr>
<td>R1R8</td>
<td>Standby sequence1</td>
<td>First alarm condition is ignored and from second alarm condition, standard alarm operates.</td>
</tr>
<tr>
<td>R1R9</td>
<td>Alarm latch and standby sequence1</td>
<td>If it is an alarm condition, it operates both alarm latch and standby sequence. When power is supplied and it is an alarm condition, this first alarm condition is ignored and from the second alarm condition, standard alarm operates.</td>
</tr>
<tr>
<td>R1R10</td>
<td>Standby sequence2</td>
<td>First alarm condition is ignored and from second alarm condition, standard alarm operates. When re-applied standby sequence and if it is alarm condition, alarm output does not turn ON. After clearing alarm condition, standard alarm operates.</td>
</tr>
</tbody>
</table>

Sensor break alarm

The function that alarm output will be ON when sensor is not connected or when sensor's disconnection is detected during temperature controlling. You can check whether the sensor is connected with buzzer or other units using alarm output contact. It is selectable between standard alarm [SbRA], or alarm latch [SbRB].
© Loop break alarm (LBA)

It checks control loop and outputs alarm by temperature change of the subject. For heating control (cooling control), when control output MV is 100% (0% for cooling control) and PV is not increased over than LBA detection band [ L b Rb ] during LBA monitoring time [ L b Rb ], or when control output MV is 0% (100% for cooling control) and PV is not decreased below than LBA detection band [ L b Rb ] during LBA monitoring time [ L b Rb ], alarm output turns ON.

Start control to ① When control output MV is 0% and PV is not decreased below than LBA detection band [ L b Rb ] during LBA monitoring time [ L b Rb ]

① to ② The status of changing control output MV (LBA monitoring time is reset.)
② to ③ When control output MV is 0% and PV is not decreased below than LBA detection band [ L b Rb ] during LBA monitoring time [ L b Rb ] loop break alarm (LBA) turns ON after LBA monitoring time.
③ to ④ Control output MV is 0% and loop break alarm (LBA) turns and maintains ON.
④ to ⑤ The status of changing control output MV (LBA monitoring time is reset.)
⑤ to ⑥ When control output MV is 100% and PV is not increased over than LBA detection band [ L b Rb ] during LBA monitoring time [ L b Rb ], loop break alarm (LBA) turns ON after LBA monitoring time.
⑥ to ⑦ When control output MV is 100% and PV is increased over than LBA detection band [ L b Rb ] during LBA monitoring time [ L b Rb ] loop break alarm (LBA) turns OFF after LBA monitoring time.
⑦ to ⑧ The status of changing control output MV (LBA monitoring time is reset.)

※When executing auto-tuning, LBA detection band [ L b Rb ] and LBA monitoring time are automatically set based on auto tuning value. When AL1, AL2 alarm operation [ RL - 1, R L - 2 ] is set as loop break alarm (LBA) [ L b Rb ], LBA detection band [ L b Rb ] and LBA monitoring time [ L b Rb ] parameter is displayed.

© SSR drive output function (SSRP function) [ S S R a R ]

- Realizing high accuracy and cost effective temperature control with both current output (4-20mA) and linear output (cycle control and phase control)
- SSRP output is selectable one of standard ON/OFF control, cycle control, phase control by utilizing standard SSR drive voltage output.
- Select one of standard ON/OFF control [ S S R a ], cycle control [ S S R a C L ], phase control [ P H R S ] at SSR drive output method S S R a R of parameter 2 group. For cycle control, connect zero cross turn-on SSR (random turn-on SSR is also available). For phase control, connect random turn-on SSR.

※When selecting phase or cycle control mode, the power supply for load and temperature controller must be the same.
※In case of selecting PID control type and phase [ P H R S ] / cycle [ C Y C L ] control output modes, control cycle [ C ] is not allowed to set.
※For AC/DC power model (TCN4 R - 22R), this parameter is not displayed and it is available only standard control by relay or SSR.
Economical Dual Display type, PID Control

- **Standard ON/OFF control mode [5×<i>d</i>]**
  A mode to control the load in the same way as Relay output type.
  (ON: output level 100%, OFF: output level 0%)

- **Cycle control mode [CW×L]**
  A mode to control the load by repeating output ON / OFF according to the rate of output within setting cycle.
  Having improved ON / OFF noise feature by Zero Cross type.

- **Phase control mode [PH×S]**
  A mode to control the load by controlling the phase within AC half cycle. Serial control is available.
  RANDOM Turn-on type SSR must be used for this mode.

© **Auto tuning [R×b]**
- Auto tuning measures the control subject's thermal characteristics and thermal response rate, and then determines the necessary PID time constant. (When control type [C×<i>d</i>] is set as P/I D, it is displayed.)
- If error [P×e×<i>y</i>] occurs during auto tuning, it stops this operation automatically.
- To stop auto tuning, change the set as OFF. (It maintains P, I, D values of before auto tuning.)

© **Input correction [i×<i>n</i>-b]**
  Controller itself does not have errors but there may be error by external input temperature sensor.
  Ex) If actual temperature is 80°C but controller displays 78°C, set input correction value [i×<i>n</i>-b] as 0.02 and controller displays 80°C.
  ※As the result of input correction, if current temperature value (PV) is over each temperature range of input sensor, it displays HHHH LLLLL.

© **Input digital filter [×<i>AR</i>] F**
  If current temperature(PV) is fluctuating repeatedly by rapid change of input signal, it refl acts to MV and stable control is impossible. Therefore, digital filter function stabilizes current temperature value.
  - For example, set input digital filter value as 0.4 sec, and it applies digital filter to input values during 0.4 sec and displays this values. Current temperature may be different by actual input value.

© **SV High/Low limit [L×<i>S</i>u / H×<i>S</i>u]**
- It sets SV high/low limit Range of using temperature within temperature range for each sensor, user can set/ change set temperature(SV) within SV high limit [H×<i>S</i>u] to SV low limit [L×<i>S</i>u]. (※L×<i>S</i>u > H×<i>S</i>u cannot be set.)
- When changing input type [i×<i>n</i>-b], SV high limit [H×<i>S</i>u] and SV low limit [L×<i>S</i>u] of using temperature will be initialized as max./min. value of sensor temperature range automatically.

© **Hysteresis [H×SS]**
- In case of ON/OFF control, set between ON and OFF intervals as hysteresis. (When control type[C×<i>d</i>] is set as 00F, it is displayed.)
- If hysteresis is too small, it may cause control output hunting (take off, chattering) by external noise, etc.

© **Manual reset [r×SS×b]**
  When selecting P/PD control mode, certain temperature difference exists even after PV reaches stable status because heater's rising and falling time is inconsistent due to thermal characteristics of controlled objects, such as heat capacity, heater capacity. This temperature difference is called offset and manual reset [r×SS×b] function is to set/ correct offset.
  - When PV and SV are equal, reset value is 50.0%. After con-trol is stable, PV is lower than SV, reset value is over 50.0% or PV is higher than SV, reset value is below 50.0%.
  - Manual reset [r×SS×b] by control result

© **Temperature unit selection [U×<i>n</i>-b]**
- A function to select display temperature unit.
  - Unit display indicator will be ON when converting temperature unit.
Cool / Heat function $[\text{o - } F \text{t}]$

Generally there are two ways to control temperature, one (heat-function) is to heat when PV is getting down(heater). The other(cool-function) is to cool when PV is getting higher (freezer).

These functions are operating oppositely when it is ON/OFF control or proportional control. But in this case PID time constant will be different due to PID time constant will be decided according to control system when it is PID control.

- Cool-function $[\text{Cool}]$ and heat-function $[\text{Heat}]$ must be set correctly according to the application, if set as opposite function, it may cause a fire. (If set cool-function $[\text{Cool}]$ at heater, it will be maintained ON and it may cause a fire.)
- Avoid changing heat-function to cool-function or cool-function to heat-function when the unit is operating.
- It is impossible to operate both function at once in this unit. Therefore, only one function should be selected only.

Control method selection $[\text{C - } \text{d}]$

It is selectable PID, ON/OFF control.

- In case of ON/OFF $[\text{o o F}]$, Hysteresis $[\text{HYS}]$ parameter is displayed.
- In case of PID $[\text{P I d}]$ mode, Proportional band $[\text{P}]$, Integral time $[\text{i}]$, and Derivative time $[\text{t}]$ parameters are displayed.

Digital input key $[\text{O + 3sec.}]$ $[\text{d I - t}]$

Parameter Operation

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Operation</th>
</tr>
</thead>
<tbody>
<tr>
<td>OFF</td>
<td>$\text{o F}$</td>
</tr>
<tr>
<td>RUN/STOP</td>
<td>$\text{S t o P}$</td>
</tr>
<tr>
<td>Clear alarm output</td>
<td>$\text{A L r E}$</td>
</tr>
<tr>
<td>Auto tunning</td>
<td>$\text{A t}$</td>
</tr>
</tbody>
</table>

Lock setting $[\text{L a C}]$

A function to prevent changing SV and parameters of each setting group. Parameter setting values are still possible to check while Lock mode is ON.

<table>
<thead>
<tr>
<th>Display</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>$\text{o F}$</td>
<td>Lock off</td>
</tr>
<tr>
<td>$\text{L a C 1}$</td>
<td>Lock parameter group 2</td>
</tr>
<tr>
<td>$\text{L a C 2}$</td>
<td>Lock parameter group 1, 2</td>
</tr>
<tr>
<td>$\text{L a C 3}$</td>
<td>Lock parameter group 1, 2, SV setting</td>
</tr>
</tbody>
</table>

Control output type selection $[\text{o U t}]$

It is selectable output type; relay output $[\text{r L y}]$, SSR drive output $[55 5]$.

Alarm output hysteresis $[\text{AHYS}]$

It displays alarm output ON and OFF interval and hysteresis is applied to both AL1 OUT and AL2 OUT.

- $[\text{AHYS}]$: 1 to 100
- Ex) AL1 alarm operation $[\text{AL 1}]$: 4

Control output MV $[\text{E r a u}]$ when input sensor line is broken $[\text{o P E n}]$ / setting error $[\text{E s 5 u}]$ occur

When input sensor line is broken or setting value error occurs, this function is to set control output. You can set ON/OFF setting for ON/OFF control. MV setting for PID control.
**Output connections**

See H-139 page for output.

- **Application of relay output type**

Keep A length as long as possible when wiring the temperature controller and the load. If wire length of A is short, counter electromotive force which occurs from a coil of magnet switch & power relay may flow in power line of the unit, and it may cause malfunction.

If wire length of A is short, please connect mylar condensers 104(630V) on the both ends of "A" (magnet coil) to protect electromotive force.

---

### Proper usage

**Simple "error" diagnosis**

- **When the load (Heater etc) is not operated**
  
  Please check operation of the OUT indicator located in front panel of the unit.
  
  If the OUT indicator does not operate, please check the parameter of all programmed mode.
  
  If indicator is operating, please check the output (Relay, SSR drive voltage) after separating output line from the unit.

- **When it displays "PE" during operation**
  
  This is a warning that external sensor is open. Please turn off the power and check the wire state of the sensor. If sensor is not open disconnect sensor line from the unit and short the input +, - terminal. Turn on the power of the unit and check the controller displays room temperature.
  
  If this unit cannot display room temperature, this unit is broken. Please remove this unit and contact our service center. (When the input mode is thermocouple, it is available to display room temperature.)

---

**Caution for using**

- The connection wire of this unit should be separated from the power line and high voltage line in order to prevent from inductive noise.
  
  For crimp terminal, select following shaped terminal (M3)

```
Max. 5.8mm
```

Please install power switch or circuit-breaker in order to cut power supply off.

- The switch or circuit-breaker should be installed near by users.

- This unit is designed for temperature controlling only. Do not apply this unit as a voltage meter or a current meter.

- In case of using RTD sensor, 3-wire type must be used. If you need to extend the line, 3-wires must be used with the same thickness as the line. It might cause temperature difference if the resistance of line is different.

- In case of making power line and input signal line close, line filter for noise protection should be installed at power line and input signal line should be shielded.

- Keep away from the high frequency instruments. (High frequency welding machine & sewing machine, big capacitive SCR controller)

- When supplying measured input, if HHHH or LLLL is displayed, measured input may have problem. Turn off the power and check the line.

- Installation environment
  
  - It shall be used indoor.
  - Altitude Max. 2000m.
  - Pollution Degree 2
  - Installation Category II.

---

**Application of SSR drive output method**

SSR should be selected by the capacity of load, otherwise, it may short-circuit and result in a fire. Indirect heated should be used with SSR for efficient working.

Please use a cooling plate or it may cause the capability deterioration, breakdown of SSR for a long usage.

Refer to the H-50 page for phase/cycle control connections.